

445-093 OCTOBER 2014-REVISED MAY 2017

IMAGENEX MODEL 881A-GS GYRO STABILIZED MULTI-FREQUENCY IMAGING SONAR

APPLICATIONS:

- ROV, AUV, & UUV
- Manned Submersibles
- Search & Recovery
- Borehole/cave work
- Drop sonar
- Scientific Research

FEATURES:

- Serial Communications
- Programmable (format available)
- · Gyro stabilized transducer steering
- Simple set-up and installation
- Full scale range from 1 m to 200 m
- Orientation module

Gyro-stabilization of the Imagenex Model 881A-GS makes the high resolution 881A sonar into a system capable of crystal clear visualization of the ocean environment from moving platforms, no longer compromised by the blurring effects of host vehicle rotation. An advanced, low drift gyro is integrated directly into the sonar head, so the sonar can now compensate for vehicle motion in real time with unprecedented accuracy, stability, and robustness.

The enhanced capabilities of the 881A-GS have not compromised the performance of the 881A sonar. On short range, this sonar scans using a 2 mm range resolution, and can auto-adjust acoustic frequency and resolution to scan up to a 200 m radius, 360° surrounding area.

The Model 881A-GS still has low power, simple setup, and small size that make it an ideal tool for large work ROV's and small inspection vehicles. On it's own it is now an amazingly simple drop sonar and borehole inspection package: just add a laptop computer and power supply and run the included Imagenex software.

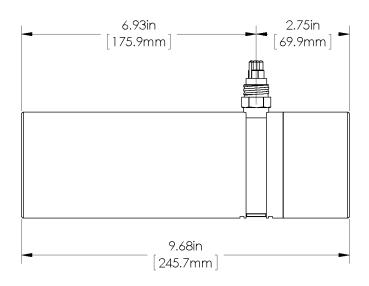


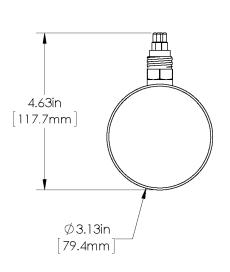
T PHONE: 02 479 2703 ~ 4

w http://www.tkec.co.kr

(E) e-mail: taekwang@tkec.co.kr

LIADDWADE			
HARDWARE			
SPECIFICATIONS:			
FREQUENCY	310 kHz, 675 kHz, or 1 MHz (standard default settings)		
	-Other frequencies can be selected through programmable		
	software configurations		
	(Tunable from 280 kHz to 1.1 MHz in 5 kHz steps)		
TRANSDUCER	Imaging type, fluid compensated		
TRANSDUCER BEAM WIDTH	310 kHz: 4° x 40°		
	675 kHz: 1.8° x 20°		
	1 MHz: 0.9° x 10°		
RANGE RESOLUTION	1 m – 4 m: 2 mm (0.08")		
	5 m & up: 10 mm (0.4")		
ORIENTATION MODULE (accuracies):			
PITCH & ROLL	± 0.1° typical		
HEADING (Magnetic)	± 1.0° typical		
MIN. DETECTABLE RANGE	150 mm (6")		
MAX. OPERATING DEPTH	1000 m and		
	3000 m available		
MAX. CABLE LENGTH	1000 m on typical twisted shielded pair (RS-485)		
INTERFACE	RS-485 serial interface @ 115.2 kbps (or optional RS-232)		
CONNECTOR	Side mounted, four conductor, wet mateable		
	(Subconn MCBH4M-AS)		
	Optional right angle or end mount connector		
POWER SUPPLY	20 – 32 VDC at less than 7 Watts		
DIMENSIONS (for both depths)	79.5 mm (3.13") diameter x 245.7 mm (9.68") length		
WEIGHT: In Air	1000 m unit: 1.6 kg (3.5 lbs)		
	3000 m unit: TBA		
In Water	1000 m unit: TBA		
	3000 m unit: TBA		
MATERIALS	1000 m unit: 6061-T6 Aluminum & Polyurethane		
	3000 m unit: Titanium, Polyurethane & 300 series stainless		
	steel		
FINISH	Hard Anodize		





TAE KWANG ELECTRONICS CORPORATION5TH FLR., K-BLDG., 3, SANGAM-RO 41-GIL,
GANGDONG-GU, SEOUL 05307, KOREA

T PHONE: 02 479 2703 ~ 4

E e-mail: taekwang@tkec.co.kr

w http://www.tkec.co.kr

SOFTWARE	Win881AL.exe	
SPECIFICATIONS:		
WINDOWS™ OPERATING SYSTEM	Windows™ XP, Vista, 7, 8, 10	
MODES	Sector, Polar and Side Scan	
GYRO MODES	North Up, Heading Up, Target Steering	
RANGE SCALES	1 m, 2 m, 3 m, 4 m, 5 m, 10 m, 20 m, 30 m, 40 m,	
	50 m, 60 m, 80 m, 100 m, 150 m, 200 m	
TRAIN ANGLES	Continuous rotation, 3° increments	
SECTOR SIZE:		
SECTOR MODE	0° – 180°, 3° increments	
POLAR MODE	0° – 357°, 3° increments, or Continuous rotation	
STEP SIZES	Slow (0.3°), Medium (0.6°), Fast (0.9°), Faster (1.2°),	
	Fastest (2.4°)	
GRID TYPES	Polar and rectangular	
FILE FORMAT	(filename).81R	
RECOMMENDED	2 GHz Pentium 4	
MINIMUM COMPUTER	256 MB RAM	
REQUIREMENTS:	20 GB Hard Disk	
	1024 x 768 Screen Resolution	

ORDERING INFORMATION:		
1000 m UNIT	Standard	881-000-400
3000 m UNIT	Standard	881-000-401
RS-232	Option	-006
End mount connector	Option	-009
Right angle connector	Option	-010
Gyro Stabilization	Option	-048

T PHONE: 02 479 2703 ~ 4

w http://www.tkec.co.kr

e-mail: taekwang@tkec.co.kr