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# 106G MiniPod, GNSS Submersible



# **Key features**

- L1 + L2 band antenna
- Submersible GNSS receiver with integrated antenna
- 6000m rated.
- Multi GNSS constellation compatibility
- Begins positioning <30s after surfacing.</li>
- Receives wide area corrections or accepts external corrections
- Internal batteries assist in the case of temporary power failure.

# **Applications**

- Deep water to transition zone operations, trenching and construction.
- Sandbank UXO crawlers
- · Surface positioning for vehicle recovery operations

#### 106G MiniPod Overview

The 106G MiniPod is a ruggedised GNSS receiver designed to survive 6000m immersion that complements the operation of a nearby standard subsea positioning beacon.

This arrangement is suited to coastal construction tasks where deep rated submersible vehicles may periodically break the surface.

Whilst submerged, positioning data is provided by a standard positioning beacon but once the vehicle breaks the surface the 106G MiniPod takes over to provide the information required, typically cabled to the vessel based positioning system via the vehicle umbilical system.

# **Technical Specification**

#### **MODEL TYPES - PHYSICAL SPECIFICATION**

Housing material: Titanium body with glass hemisphere.

| Model Part Number | Survival Depth | Diameter | Length | Weight air/water |
|-------------------|----------------|----------|--------|------------------|
| BCN- 106G         | 6000m          | 119mm    | 289mm  | 7kg / 4kg        |

#### **ELECTRICAL SPECIFICATION**

| Battery type | Rechargeable. NiMH |
|--------------|--------------------|
| Battery life | 4 hours            |

### **ACCURACY (DEPENDENT ON CORRECTIONS)**

| RMS 67%     | Horizontal  | Vertical    |
|-------------|-------------|-------------|
| RTK         | 8mm + 1 ppm | 15mm + 2ppm |
| SBAS (WAAS) | 0.3m        | 0.6m        |
| Unaided     | 1.2m        | 2.4m        |
| Atlas H10   | 0.04m       |             |
| Atlas H30   | 0.15m       |             |
| Atlas H100  | 0.50m       |             |

 $Accuracies \ dependent \ on \ multipath \ environment, \ number \ of \ satellites \ in \ view, \ geometry \ and \ ionospheric \ conditions$ 

# WARM UP TIME (TYPICAL)

| From cold  | <60s (No almanac or real time clock) |  |
|------------|--------------------------------------|--|
| Warm start | <30s (Almanac & RTC, no position)    |  |
| Hot start  | <10s                                 |  |



#### CONNECTIVITY

| Connector               | 8 pin MCBH connector (male)  |
|-------------------------|--|
| Power                   | 18-36VDC<br>24v 160mA nominal  |
| Communication           | RS232 (2 bi-directional ports) RS485 (2 wire bi-directional)             |
| Position protocol       | NMEA 0183 protocols supported  |
| Refresh rate            | 1Hz standard, 10Hz, 20Hz optional  |
| Correction I/O protocol | Hemisphere GNSS proprietary, ROX Format, RTCM v2.3, RTCM v3.2, CMR, CMR+ |
| 1pps                    | 3.3V, 1ms pulse width, 20mA optional                                     |

#### **SAFETY AND MANAGEMENT**

- Automatic Pressure Relief Valve (PRV)
- External on/off switch

#### **OPTIONS**

 RTK Base and Rover activation for GNSS receiver. Allows full RTK fixed position quality. RTK float can be achieved as standard without additional option



